

COURSE SYLLABUS

Course:Differential EquationsNumber:Math 317Credit-Hours:3 credits [semester credit hours]

Course Description: Studies methods of solution of ordinary differential equations with applications in science and engineering. Extensive use is made of the method of Laplace transforms.

Prerequisites: Successful completion (C- or higher) of MATH 214 (Calculus II) or equivalent.

Course Workload: 3 semester credit hours • 3 student work hours per credit hour • 14 week Carnegie semester = 126 hours student course workload average

Examination Requirements: Proctored written final examination must be passed at 60% or higher to earn passing grade in course. "B" and "A" grade paths have additional examinations. See <u>http://www.distancecalculus.com/grades/</u> for more information.

Course Professor: Robert R. Curtis, Ph.D. < robert@distancecalculus.com>

University Information: Roger Williams University, University College, 1 Empire Plaza, Providence, RI, USA 02903. Accredited by New England Commission of Higher Education (NECHE). See <u>https://www.rwu.edu/academics/accreditations</u> for more information.

E-Textbook: "Differential Equations & Mathematica" by Davis/Porta/Uhl et al Mathematics Software: Mathematica[™] Computer Algebra & Graphing System

Detailed Syllabus

- 1. Getting Started
 - 1.1. Email and Chat
 - 1.2. Learning About the Course
 - 1.3. Required Hardware
 - 1.4. Software Fundamentals
- 2. Basic Differential Equations
 - 2.1. Unforced
 - 2.2. Forced
 - 2.3. Steady State
 - 2.4. Personal Finance
 - 2.5. Step Function and Dirac Delta Function
 - 2.6. Tangent Vectors
 - 2.7. Initial Conditions
 - 2.8. Integration Factors
- 3. Second-Order Differential Equations
 - 3.1. Overdamped and Underdamped Oscillators
 - 3.2. Linear Forced and Unforced Oscillators
 - 3.3. Homogeneous Equations
 - 3.4. Inhomogeneous Equations
 - 3.5. Characteristic Equations
 - 3.6. Euler's Formula
 - 3.7. Impulse Forcing
 - 3.8. Convolution Integrals Methods
 - 3.9. Springs and Electrical Charges
 - 3.10. Resonance
 - 3.11. Higher Order Equations
- 4. Laplace Transforms
 - 4.1. Laplace Transform Method
 - 4.2. Introductory Fourier Analysis and Fourier Fitting
- 5. Graphical Analysis of Differential Equations
 - 5.1. Euler's Method
 - 5.2. Flow Plots and Trajectories
 - 5.3. Phase Lines
 - 5.4. Predator-Prey Model
 - 5.5. Logistic Harvesting
 - 5.6. Bifurcation Points
 - 5.7. Sensitivity to Initial Conditions

6. Non-Linear First-Order Differential Equations

- 6.1. Autonomous Equations
- 6.2. Non-Autonomous and Other Equation Types
- 6.3. Separation of Variables Solving Method
- 7. Linear Systems of Differential Equations
 - 7.1. Flows, Trajectories, and Vector Fields
 - 7.2. Conversion Between Higher Order ODEs and Linear Systems
 - 7.3. Eigenvalues, Eigenvectors, and Classification of Solutions